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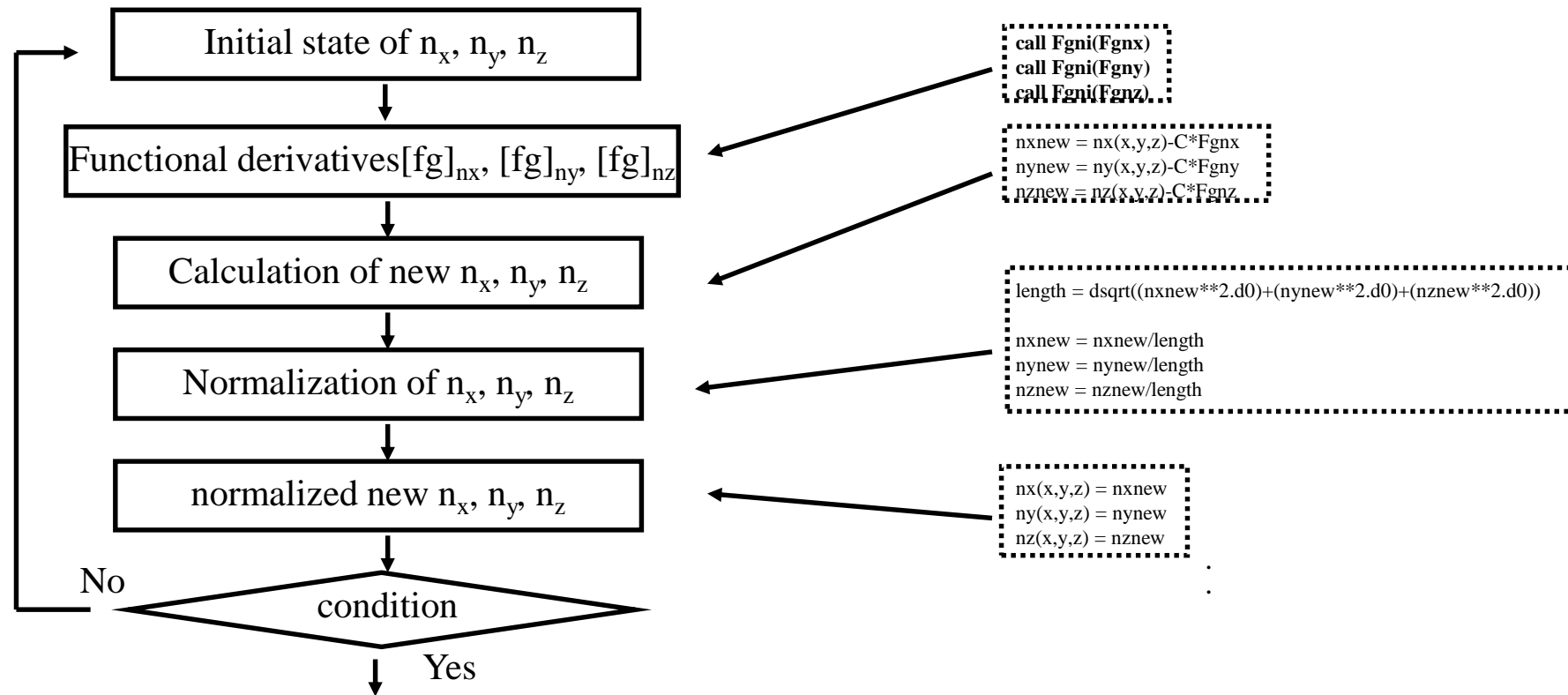
# Vector simulation

## 보충자료

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# Vector Method

- Flow chart for calculation (Vector method)(LC3D by James Anderson)



# Vector Method

- *Euler-Lagrange* equations for vector method

$$0 = -[f_g]_{n_i}$$

$$0 = -[f_g]_V = \nabla \cdot D = \nabla \cdot (\epsilon_0 \epsilon_r \nabla V)$$

$[f_g]_{n_i}$  : *Functional Derivatives by  $n_i$*

$[f_g]_V$  : *Functional Derivatives by voltage  $V$*

$$[f_g]_{n_i} = \frac{\partial f_g}{\partial n_i} - \frac{d}{dx} \left( \frac{\partial f_g}{\partial n_{i,x}} \right) - \frac{d}{dy} \left( \frac{\partial f_g}{\partial n_{i,y}} \right) - \frac{d}{dz} \left( \frac{\partial f_g}{\partial n_{i,z}} \right)$$

$$n_{i,x} = \frac{\partial n_i}{\partial x}, \quad n_{i,y} = \frac{\partial n_i}{\partial y}, \quad n_{i,z} = \frac{\partial n_i}{\partial z}$$

# Vector Method

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- Oseen-Frank Equation's Vector form
- In general, deformation of LC directors (Elastic term) can be achieved from *Oseen-Frank* equation (*Vector form*)

$$f_s = \frac{1}{2} K_{11} (\nabla \cdot n)^2 + \frac{1}{2} K_{22} (n \cdot \nabla \times n)^2 + \frac{1}{2} K_{33} (n \times \nabla \times n)^2$$

# Vector Method

$$\text{splay} = \frac{1}{2} K11 \left( \left( \frac{\partial}{\partial x} nx(x, y, z) \right) + \left( \frac{\partial}{\partial y} ny(x, y, z) \right) + \left( \frac{\partial}{\partial z} nz(x, y, z) \right) \right)^2$$

$$\begin{aligned} K11 &= 0.0000000000132 \\ K22 &= 0.0000000000065 \\ K33 &= 0.0000000000183 \\ Q0 &= 0 \end{aligned}$$

*twist*

$$\begin{aligned} &= \frac{1}{2} K22 \left( (nx(x, y, z)) \left( \left( \frac{\partial}{\partial y} nz(x, y, z) \right) - \left( \frac{\partial}{\partial z} ny(x, y, z) \right) \right) + (ny(x, y, z)) \left( \left( \frac{\partial}{\partial z} nx(x, y, z) \right) - \left( \frac{\partial}{\partial x} nz(x, y, z) \right) \right) \right. \\ &\left. + (nz(x, y, z)) \left( \left( \frac{\partial}{\partial x} ny(x, y, z) \right) - \left( \frac{\partial}{\partial y} nx(x, y, z) \right) \right) + q0 \right)^2 \end{aligned}$$

*bend*

$$\begin{aligned} &= \frac{1}{2} K33 \left( \left( ny(x, y, z) \left( \frac{\partial}{\partial x} ny(x, y, z) \right) - ny(x, y, z) \left( \frac{\partial}{\partial y} nx(x, y, z) \right) - nz(x, y, z) \left( \frac{\partial}{\partial z} nx(x, y, z) \right) + nz(x, y, z) \left( \frac{\partial}{\partial x} nz(x, y, z) \right) \right)^2 \right. \\ &+ \left( nz(x, y, z) \left( \frac{\partial}{\partial y} nz(x, y, z) \right) - nz(x, y, z) \left( \frac{\partial}{\partial z} ny(x, y, z) \right) - nx(x, y, z) \left( \frac{\partial}{\partial x} ny(x, y, z) \right) + nx(x, y, z) \left( \frac{\partial}{\partial y} nx(x, y, z) \right) \right)^2 \\ &\left. + \left( nx(x, y, z) \left( \frac{\partial}{\partial z} nx(x, y, z) \right) - nx(x, y, z) \left( \frac{\partial}{\partial x} nz(x, y, z) \right) - ny(x, y, z) \left( \frac{\partial}{\partial y} nz(x, y, z) \right) + ny(x, y, z) \left( \frac{\partial}{\partial z} ny(x, y, z) \right) \right)^2 \right) \end{aligned}$$

# Vector Method

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Surface Top tilt : 0  
Surface Bottom tilt : 0  
Bulk : 90

